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The Application of Multiderivative Infrared Spectroscopy to Iodine Number Determination

Jeffrey C. Lowry

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THE APPLICATION OF MULTIDERIVATIVE INFRARED SPECTROSCOPY TO IODINE NUMBER DETERMINATION

by

Jeffrey C. Lowry

A Thesis
Submitted to the
Faculty of The Graduate College
in partial fulfillment of the
requirements for the
Degree of Master of Arts
Department of Chemistry

Western Michigan University
Kalamazoo, Michigan
December 1984
The Food and Drug Administration requires the disclosure of total unsaturation of commercial products as an indication of nutritional value. This unsaturation is a guide to the expected stability of food additives, such as edible oils and foods in which they are used. Unsaturation is typically evaluated as an iodine number, calculated for these additives based on their consumption of iodine through addition across the carbon-carbon double bonds. This titration method can typically take 45 minutes.

The investigation presented develops an alternative method for determining iodine numbers of some common oils using a computerized infrared spectrophotometer. The quantitation technique employed involves multiderivative spectroscopy. Results of the analytical data give iodine numbers with relative errors of approximately 1 percent. The higher order derivative quantitation technique is limited by the noise within the spectrophotometer. The analysis time, as compared to the titration method, is reduced by 20 fold.
ACKNOWLEDGEMENTS

I would like to thank Jim Howell for his support, patience and time throughout the years. My appreciation is also extended to my family, without whom this thesis would not be possible. Finally, to my best friend, Dianne, for that continuing supply of moral support.

Jeffrey C. Lowry
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# TABLE OF CONTENTS

ACKNOWLEDGEMENTS ................................................................. ii

LIST OF TABLES ........................................................................ v

LIST OF FIGURES ........................................................................ vi

Chapter

I. INTRODUCTION ................................................................. 1
   Infrared Spectroscopy ........................................................... 1
   Derivative Spectroscopy ......................................................... 4
   Computers ............................................................................ 10
   Proposed Problem ................................................................. 16

II. DESIGN AND CONSTRUCTION ........................................... 21
   Infrared Spectrophotometer .................................................. 21
   Heathkit ET-3400 Trainer Interface ..................................... 21
      Hardware Description ......................................................... 21
      Input ............................................................................... 22
      Output ............................................................................. 23
      Software Description ........................................................ 26
      Input ............................................................................... 26
      Data Processing ................................................................ 28
      Output ............................................................................. 28
   Apple/Isaac Interface ............................................................ 29
      Hardware Description ......................................................... 29
      Input ............................................................................... 29
      Output ............................................................................. 32
<table>
<thead>
<tr>
<th>Section</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Software Description</td>
<td>32</td>
</tr>
<tr>
<td>Input</td>
<td>32</td>
</tr>
<tr>
<td>Output</td>
<td>33</td>
</tr>
<tr>
<td>Systems Comparison</td>
<td>34</td>
</tr>
<tr>
<td>III. EXPERIMENTAL</td>
<td>35</td>
</tr>
<tr>
<td>Procedure</td>
<td>35</td>
</tr>
<tr>
<td>Chromophore Study I</td>
<td>36</td>
</tr>
<tr>
<td>Chromophore Study II</td>
<td>38</td>
</tr>
<tr>
<td>Selected Oil Study</td>
<td>42</td>
</tr>
<tr>
<td>IV. DISCUSSION</td>
<td>47</td>
</tr>
<tr>
<td>Advantages and Disadvantages</td>
<td>47</td>
</tr>
<tr>
<td>Conclusion</td>
<td>48</td>
</tr>
<tr>
<td>Recommendations</td>
<td>48</td>
</tr>
<tr>
<td>APPENDIX A</td>
<td>50</td>
</tr>
<tr>
<td>APPENDIX B</td>
<td>60</td>
</tr>
<tr>
<td>APPENDIX C</td>
<td>86</td>
</tr>
<tr>
<td>REFERENCES</td>
<td>95</td>
</tr>
</tbody>
</table>
LIST OF TABLES

1. Common Fatty Acids from the Hydrolysis of Oils ........ 17

2. Selected Derivative Spectral Values as a Function of \text{C=C} Chromophore Concentration ......................... 37

3. Slope Values from the Least Squares Analysis of Concentration of \text{C=C} Chromophore vs. Selective Derivative Values .......... 41

4. Iodine Numbers of Selected Oils ................................ 44

5. Iodine Numbers of Peanut Oil vs. Olive Oil ................ 46
LIST OF FIGURES

1. Common Subdivisions of the Infrared Region .................. 1
2. Overlapping Absorbance Curves .................................. 8
3. Absorption Maxima and Derivative Spectra .................. 9
4. Structure of a Basic Digital Computer ...................... 11
5. Triacylglycerol .................................................. 16
6. Infrared Spectrum of Soybean Oil ........................... 19
7. MC6800 Microprocessor Interface System .................. 24
8. Apple/Isaac Interface System .................................. 31
9. Plot of Concentration of 1-Hexene vs. First Derivative Maxima Values ........................................ 39
A-1. Address Assignments of PIA Registers .................... 52
A-2. PIA Interface .................................................. 52
A-3. Addressing to PIA ............................................. 54
A-4. Model 1234 Analog-to-Digital Converter .................. 56
A-5. TTL Conversion Circuit ..................................... 57
A-6. Reset Switch Circuit ......................................... 58

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CHAPTER 1

INTRODUCTION

Infrared Spectroscopy

Infrared (I.R.) spectroscopy is one of the more widely used instrumental techniques for studying the structure of chemical compounds. Since its discovery by Sir William Herschel in 1800 (1), it has found application in many disciplines throughout the scientific world. Infrared spectroscopy has become very important to the physicist, the biologist, and the chemist as a tool for solving a wide variety of problems. Infrared spectroscopy provides investigators with a powerful insight into molecular structure and chemical identification.

The infrared region of the electromagnetic spectrum lies between the visible and microwave regions. This region starts near the red end of the visible spectrum at 14,000 cm\(^{-1}\) or 0.7 \(\mu\)m and extends to approximately 10 cm\(^{-1}\) or 1000 \(\mu\)m. Both micrometers (\(\mu\)m) and wavenumbers in reciprocal centimeters (cm\(^{-1}\)) are used to characterize infrared wavelengths. As shown in Figure 1, the infrared spectrum can be divided into three subdivisions according to the different kinds of molecular

<table>
<thead>
<tr>
<th></th>
<th>NIR</th>
<th>Fundamental</th>
<th>FIR</th>
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</thead>
<tbody>
<tr>
<td>(\tilde{\nu}(\text{cm}^{-1}))</td>
<td>14,000</td>
<td>4000</td>
<td>1250</td>
</tr>
<tr>
<td>(\lambda(\mu\text{m}))</td>
<td>0.75</td>
<td>2.5</td>
<td>8</td>
</tr>
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Figure 1. Common Subdivisions of the Infrared Region

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information which they can provide. The first region, ranging from 14,000 to 4,000 cm\(^{-1}\), is called the near infrared (NIR) region. Absorption bands in the NIR region result from overtones or combinations of hydrogen stretching vibrations. This region can be easily used for quantitative analysis of certain functional groups containing unique hydrogen atoms within a compound.

The majority of qualitative and quantitative work is done in the middle region or the fundamental infrared region. This region's absorption bands result from vibration and rotation of functional groups. The fundamental region is divided into a group frequency region from 4,000 to 1,250 cm\(^{-1}\) and a fingerprint region from 1,250 to 400 cm\(^{-1}\). In the group frequency region the absorption bands tend to be characteristic of specific groups of atoms within the structure of the molecule. The fingerprint region bands, on the other hand, result from effects of the total molecular structure.

The far infrared (FIR) region gives information mainly about rotational transitions, vibrational modes of crystal lattices, and skeletal vibrations of large molecules. This region starts at 400 cm\(^{-1}\) and extends to the microwave region at 10 cm\(^{-1}\). It is generally not useful for quantitative analysis due to the relatively poor signal-to-noise ratio implicit in long wavelength spectroscopy and by the relatively low intensity of the absorption bands (1).

Most quantitative infrared spectroscopic measurements are performed in the fundamental region. Several difficulties commonly occur in quantitative I.R. analysis. The major problem arises from an instrumental source and is commonly referred to as stray or scattered
radiation. Due to the small radiation energy available from I.R.
sources, relatively wide slit widths are used. This causes a propor-
tional increase in the scattered radiation and a broadening of the
absorption bands. This distortion in the maxima causes deviations from
Beer's Law (2), the basic quantitative relationship in spectroscopic
analysis.

Another difficulty in I.R. quantitative analysis is the uncer-
tainty in determining the 100 percent transmittance level. This un-
certainty is caused by the variability of path length of the very thin
cells commonly used in I.R. spectroscopy. The problem of determining
the 100 percent level causes variations in the baseline over the width
of an absorption maximum. Thus, it is necessary to draw the best approx-
imate baseline across the peak for quantitation. This method is referred
to as the base-line method and assumes that the background is linear
over the width of the band. This assumption is often unjustified as
bands overlap, thus producing error in the peak height measurements.

Other common sources of error in quantitative I.R. arise from
solvent absorption, atmospheric absorption (humidity and carbon dioxide),
and heat of radiation. As absorption cells are exposed to the fairly
intense beam of infrared radiation, a warming effect occurs. The
result is that the temperature of the solution increases causing the
absorption bands to vary.

In spite of all these problems, infrared spectroscopy can be used
to effect quantitative analyses with accuracies on the order of 1 per-
cent (1). In order to achieve this, extreme care must be taken to use
only the best analytical techniques. These techniques include: choosing
the analytical wavelength for minimum interference, adjusting the sample thickness and concentration such that transmittance of the analytical band is between 30 and 40 percent, selecting the optimum slit width for highest signal-to-noise ratio without losing required resolution, preparing the standards at expected sample concentrations, and minimizing the atmospheric interferences.

Derivative Spectroscopy

Derivative spectroscopy is a relatively new analytical technique. Even though it was introduced more than twenty-five years ago, it has been accepted only hesitantly. This was partly due to the high cost of instrumentation. Reliable derivatives can now be taken electronically and consequently this has resulted in a significant reduction in the cost of instrumentation. The derivative of a spectrum (3) is a graphic representation of the mathematical differentiation of an absorbance spectrum.

\[ \text{1st derivative} = \frac{dA}{d\bar{v}} \]  

(1)

where \( A = \) absorbance and \( \bar{v} = \) wavenumber.

Actually, most electronically generated derivative spectra are differentiating the change in the absorbance signal with respect to the time, rather than the wavelength or wavenumber (4). However, since spectra are collected at a constant wavelength scanning speed, these functions become equivalent.

\[ \frac{dA}{dt} = \frac{dA}{d\bar{v}} \]  

(2)

where \( t = \) time.
There are generally four methods for obtaining derivative spectra. The first and most expensive is to use a specially designed optical instrument. This instrument requires two monochromators to produce two separate scans at the same time. This method, referred to as dual-wavelength (5), scans simultaneously with both monochromators one of which has a small wavelength offset relative to the other. This produces the derivative by providing a difference in the absorbance readings between the two monochromators with respect to the difference in their wavelength.

The second method for producing derivative spectra also employs optical modification of the instrument. In this method, called wavelength modulation (6), the wavelength to which the monochromator is set is repetitively and rapidly scanned back and forth over a small spectral interval. This modulation interval produces an alternating current at the detector which represents the derivative of the spectra with respect to wavelength. Both the dual-wavelength and the modulation wavelength methods have been limited to first derivative spectroscopy.

More recently, derivative spectra have been taken using electronic circuits. Electronic circuits use the original output of the detector to produce the derivative instead of extensive instrumental modification. This method, referred to as electronic differentiation (3), is achieved by using an operational amplifier in the differentiator configuration. The signal from the detector is connected to the amplifier to produce the first derivative of the spectra. Multiderivative spectra can be produced by connecting together a series of differentiating
amplifiers. The major problem involved with the electronic differentiation technique results from the noise introduced into the spectra by the operational amplifiers.

As a result of advancements in computer interfacing the fourth method, numeric analysis (3), has become possible. The analog signal from the detector is converted to a digital signal using an electronic circuit called an analog-to-digital (A/D) converter. These data points, which represent absorbance readings versus wavelength, are stored in memory within a computer from the A/D. The digital spectrum is then numerically differentiated by subtracting consecutive absorbance readings. Therefore, the derivative by this technique is the change in absorbance with respect to the change in wavelength which can be a good approximation of the true derivative (5).

$$\lim_{\Delta v \to 0} \frac{\Delta A}{\Delta v} = \frac{dA}{dv}$$

where $\Delta A = \text{change in absorbance}$ and $\Delta v = \text{change in wavenumber}$. The validity of this equation is improved as the change in wavelength increments become smaller. The limit of change in wavelength is inherently restricted by the resolution of the spectrophotometer used. Higher order derivatives are easily obtained by repetitive differentiation by the computer.

The derivative technique has found many applications throughout the field of spectroscopy. Derivative spectroscopy has been applied in UV-visible (3), flame emission (7), flame absorption (8), luminescence (7), fluorescence (9), and also infrared (10,11) spectroscopic instruments. Most experimentation has been performed in the UV-visible
region and has been restricted to the use of the first derivative. The principal advantage of derivative measurements is the improvement in the detectability of minor spectral features. This spectral enhancement reduces the potential for measurement errors caused by overlapping and unresolved bands. Minor differences in the spectra can be so enhanced, that quantitation can become possible.

The derivative is a measure of the rate change in the slope of the spectra. Figure 2 shows the absorbance spectra obtained for compounds A, B, and a mixture of A and B. Between wavelengths c and d, the rate change in the slope for spectra B is greater than that for A. Over the same wavelength range on spectra A + B, the rate change in the slope is more sensitive to changes in compound B than it is to changes in compound A. Thus, the derivative emphasizes slope change with respect to wavelength and can sequentially provide selectivity of B relative to A.

The application of quantitative derivative spectroscopy is based on the measurement of the maxima and minima of the derivative spectra. Figure 3a depicts two overlapping absorption bands. Figure 3b depicts the corresponding derivative maxima. The derivative maximum with the greatest response relative to concentration are usually used for quantitation. Occasionally a lesser maximum may be used in order to improve selectivity.

Most derivative spectroscopy performed in the infrared region has been done in the group frequency region between 4 and 8 μm. In several investigations (10,11), the half-width peak height ratios for the overlapping bands were in the order of 1:2. The limiting factor in
Figure 2. Overlapping Absorbance Curves

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Figure 3. Absorption Maxima and Derivative Spectra

(a) Unresolved Absorption Bands

(b) First Derivative of Absorption Bands

(c) Second Derivative of Absorption Bands

(d) Third Derivative of Absorption Bands
derivative infrared spectroscopy is the inherent noise accompanying the signal. As the signal-to-noise ratio decreases within the spectra, the error in the derivative measurements becomes more significant.

Computers

The computer has made a dynamic impact on modern scientific instrumentation. It has made data acquisition, data processing, and instrument control extremely efficient and simple. Many modern spectrophotometric instruments are being designed with computer interfaces. This makes derivative spectroscopy possible in the majority of instruments currently available.

The digital computer (12) performs operations in response to commands called instructions. To perform a task, the computer uses a sequence of these instructions called a program. The device within the computer that executes the program is referred to as the central processing unit (CPU). Most CPUs include a circuit that provides arithmetic and logic operations (ALU) and a variety of registers for temporary data storage. This CPU which contains only a few integrated circuits is referred to as a microprocessor. In most smaller computers, the microprocessor is the CPU. This type of computer is called a microcomputer.

The principal component of the microcomputer is the microprocessor or CPU. The CPU controls all main communication to and from the computer through electrical lines called the processor bus. As shown in Figure 4 all other parts of the computer, including input/output devices and memory, are connected to the CPU through the data, address, and control
Figure 4. Structure of a Basic Digital Computer

- Central Processing Unit
- Arithmetic Logic Unit
- Resistor
- Program Counter
- Control Logic
- Memory
- Input Interface
  - Disc
  - Tape
  - Clock
  - A/D Converter
  - Keyboard
- Output Interface
  - Disc
  - Tape
  - D/A Converter
  - Printer
  - Display
- Data Bus
- Address Bus
- Control Bus
lines of this bus. The control bus uses the data and address busses to input into the CPU (read) and output from the CPU (write).

The standard microprocessor today is an 8-bit processor. Examples are the INTEL 8080A and 8088, the Zilos Z80, the Motorola MC6800, the MOS Technology MCS6500, and the Signetics 2650 (13). These microprocessors are the building blocks for most microcomputers on the market. More recently, 16-bit microprocessors have been introduced. These processors have superior speed over the conventional 8-bit processors. The most widely used 16-bit microprocessors are the Motorola MC68000, the Zilos Z8000, the Intel 8086, the Texas Instrument 9900, the Digital Equipment LSI-11, and the Fairchild 9940 (14).

Within the computer, the CPU has a system of data storage and retrieval called the memory. The memory contains space for both program, needed to perform the current task, and data storage. There are two types of memory. The first is the read-write memory. The binary digits within this type of memory can be changed, as well as read by the CPU. Read-write memory is commonly referred to as random access memory or RAM. The second type of memory is called read only memory or ROM. The binary digits of the ROM can be read, but not changed by the CPU.

Data are transferred to the microcomputer as binary digital signals. There are two ways to input and output digital signals. The first is called parallel communication (12,15). Parallel communication devices latch on to eight bit digital words from a peripheral source and allow the computer to access this information through the data bus. They also hold data from the computer in their "latches" for use by a
peripheral device. The data transferred between a parallel communication device and a peripheral source is in the form of a parallel digital word. Most parallel communication devices are programmable. These devices, called programmable parallel input-output devices (PIO), perform a variety of functions. The PIO provides address decoding, data I/O buffering, and status information gathering from the peripheral device. Through internal registers, the PIO can be programmed by the computer to input or output data from any selected bit of the parallel port. Due to the address decoder, the computer can treat the device as addressable memory. Parallel communication devices supply parallel digital word communication between the computer and peripheral devices.

The other type of digital communication is called serial communication (12,15,16). Instead of latching eight bits of parallel data, a serial device gathers data on a single line, one bit at a time, until it has the complete eight bit word. There are two ways in which the serial transmission may be utilized. The first is synchronous transmission which requires the computer and the peripheral device to concurrently know when data transmission starts and ends. Thus, a consistent time interval must be utilized between the computer and the peripheral to transmit data. The second serial transmission type is asynchronous data transmission. In this type of communication, the peripheral device signals the computer that it has data to be transmitted. Upon receiving the proper responses from the computer, the peripheral device sends the data. Serial communication devices have two functions: to take parallel data and convert it to serial bit streams, and to take a serial stream and convert it to parallel data. The
Standard serial device is called the universal synchronous-asynchronous receiver-transmitter (USART).

Parallel and serial communication devices are the basic building blocks in data acquisition systems from the real world. Within the computer, all data transfer is achieved in the digital world. Outside the computer, in the real world, most measurements or data transfer are analog. Analog signals or voltage fluctuations assume a continuous range of values, whereas digital signals assume only a finite number of values. For an input signal to go into the computer, an analog to digital (A/D) conversion must take place. For a digital signal to be understood in the real world, a digital to analog (D/A) conversion must take place.

The device within an interface system that is the link from the real (analog) world to the computer (digital) world is called an analog to digital converter. There are generally four techniques for A/D conversion (15-17). The first is the successive approximation. This technique generates an initial guess of the input value, converts it to an analog value, and then compares it to the actual input. Depending on the result of the comparison, the initial guess will be increased or decreased. Successive approximation is one of the most frequently used A/D converter with microprocessor interface systems because of the high speed, high resolution, and low cost.

The second technique for A/D conversion is called integration. The dual slope integrating A/D is the basic type of integrating converter. This method measures the time it takes for a capacitor to charge to an unknown voltage and to discharge under an unknown reference
voltage. The ratio of the times measured equals the ratio of the unknown and known voltages. This technique is often too slow to use for many microprocessor interfacing applications. It is commonly used in digital voltmeters because of its excellent precision and noise immunity.

The counter type converter is the third type of A/D conversion. In this technique, the analog input voltage is compared with the output of a D/A. The input of the D/A is supplied by a counter. When the reference voltage from the D/A exceeds the unknown voltage, the output of the comparator turns off the counter. The value in the counter is proportional to the unknown voltage. The speed of this technique is dependent on the unknown voltage.

The fourth technique for A/D conversion is called parallel conversion. This technique of direct comparison converts simultaneously all possible digital values into their analog form, and compares them to the input signal. This method is extremely fast, but its precision is poor.

The device within an interface system which is the link from the digital world to the analog world is the digital to analog converter (12,15-17). The basic D/A converter used today is called the weighted resistor ladder. In the resistor ladder technique, a variety of resistors are connected in a parallel configuration to a reference voltage source through switches. Each resistor represents a bit in the digital value. The most significant bit of the digital number has the least resistance. Thus, as a digital value appears, it closes the respective switches and an analog value is produced through the resistors. Fixed gained
amplifiers are connected at the output of the ladder to increase the analog value. Most D/A converters use this basic concept of laddered resistors. The precision of the ladder D/A converter is dependent on the precision of the resistors used.

D/A and A/D converters are the essential connection between the digital and analog worlds. Within an interface system, they provide data acquisition and control of the real world through the computer world.

Proposed Problem

The U.S. Food and Drug Administration requires the disclosure of total unsaturation in food additives, such as edible oils. The total unsaturation of an oil is an indication of the nutritional value, as well as a partial guide to its expected stability. Food technologists use the term iodine number as an expression of the level of unsaturation in a sample. Iodine number of an oil is defined as the number of grams of iodine absorbed by 100 grams of oil (18).

Oils are esters of glycerol and fatty acids. As shown in Figure 5, the general structure of an oil is a triacylglycerol.

\[
\begin{align*}
\text{CH}_2\text{-O-C-R} \\
\text{CH-O-C-R'} \\
\text{CH}_2\text{-O-C-R''}
\end{align*}
\]

Figure 5. Triacylglycerol

Hydrolysis of common oils yields acyl (R) groups or unsaturated
fatty acids, some of which are shown in Table 1. The carbon-carbon

Table 1
Common Fatty Acids from the Hydrolysis of Oils

<table>
<thead>
<tr>
<th>Acid</th>
<th>Structure</th>
</tr>
</thead>
<tbody>
<tr>
<td>Oleic Acid</td>
<td>( \text{CH}_3(\text{CH}_2)_7\text{CH}=\text{CH}(\text{CH}_2)_7\text{COOH} )</td>
</tr>
<tr>
<td>Linoleic Acid</td>
<td>( \text{CH}_3(\text{CH}_2)_4\text{CH}=\text{CH}-\text{CH}_2\text{CH}=\text{CH}-(\text{CH}_2)_7\text{COOH} )</td>
</tr>
<tr>
<td>Linolenic Acid</td>
<td>( \text{CH}_3\text{CH}_2\text{CH}=\text{CHCH}_2\text{CH}=\text{CHCH}_2\text{CH}=\text{CH}-(\text{CH}_2)_7\text{COOH} )</td>
</tr>
<tr>
<td>Eleostearic Acid</td>
<td>( \text{CH}_3(\text{CH}_2)_3\text{CH}=\text{CH}-\text{CH}=\text{CH}-\text{CH}=\text{CH}-(\text{CH}_2)_7\text{COOH} )</td>
</tr>
<tr>
<td>Ricinoleic Acid</td>
<td>( \text{CH}_3(\text{CH}_2)_5\text{CH}=\text{CH}_2\text{CH}=\text{CH}=\text{CH}_2\text{CH}=\text{CH}-(\text{CH}_2)_7\text{COOH} )</td>
</tr>
</tbody>
</table>

The double bonds of the fatty acids are the active reaction sites of the oil utilized for the determination of the iodine number. The iodine number is traditionally obtained from a titration technique called the Wijs or Hanus method (19). In these titrations excess iodine is added to a sample of an oil in order to add across the carbon-carbon double bonds. The absorbed iodine is determined by back titration of the unreacted iodine with sodium thiosulfate. The iodine solutions for each method are somewhat different. The Wijs titration adds chlorine to increase the reactivity of the iodine solution, whereas the Hanus titration adds bromine (20). The typical reaction time of the oil and the iodine solution is 30 to 45 minutes. Mercuric acetate can be added to the iodine solutions to speed the reaction time to 3 to 5 minutes (19). Total analysis time for an oil using these titration methods is at least 45 minutes.

Another method for determining iodine number of an oil is the use of a refractometer (21). The refractive indices of an oil can be measured before and after iodination with the iodine solution. A ratio
of the refractive indices of a standard versus an unknown oil corresponded to the iodine number of the unknown oil.

Iodine numbers have been determined using nuclear magnetic resonance, Raman spectroscopy, and electrolytic instruments. Although iodine number determinations have been obtained through a variety of instruments, the sodium thiosulfate titration remains the standard method used by the Association of Official Agriculture Chemists (A.O.A.C.) (20).

More recently infrared spectroscopy has been used to obtain iodine numbers comparable to the titration methods (22). The infrared spectrum of a typical oil (soybean) is shown in Figure 6. Two distinct bands are obtained due to the carbon-carbon double bonds within the oil. The first is at 3018 cm⁻¹. This band is caused by the alkene carbon to hydrogen stretching vibrations. Also in the same proximity is the band caused by alkane carbon to hydrogen stretching vibrations. Because of the high degree of overlap, the band at 3018 cm⁻¹ can not reliably be used for quantitation of iodine numbers. A second band due to the carbon-carbon double bond stretching vibrations is isolated at 1654 cm⁻¹. This weaker band can be used for iodine number determinations in neat oils. Due to the large background caused by the carbon-oxygen band at 1750 cm⁻¹, a correction method must be employed to facilitate quantitation. A computer controlled background correction method has been used to obtain peak height measurements of the band at 1654 cm⁻¹ (22). Standard oils with known iodine values were used to compare with standard deviations of 1 percent or less were obtained using the computerized infrared background correction method. The time for an analysis

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Figure 6. Infrared Spectrum of Soybean Oil
was 2 minutes.

The to maxima of an oil at 1654 and 1750 cm\(^{-1}\) overlap each other significantly. The partially resolved carbon-carbon double bond peak provides an excellent opportunity to employ the derivative technique. Derivative infrared spectroscopy should improve the detectability of the partially resolved peak at 1654 cm\(^{-1}\). This should produce an improvement in quantitation of the iodine number of an oil.
CHAPTER II

DESIGN AND CONSTRUCTION

Infrared Spectrophotometer

The infrared spectrophotometer used in the study was a Beckman Acculab 8 (23,24). This instrument employs a rotating wedge filter and a 100-line/mm grating (used in two orders) to provide a spectral range of 4000 to 600 cm\(^{-1}\). The order break of the scan is at 2000 cm\(^{-1}\). The source of radiation for the double beam instrument is a nichrome wire. The resolution produced by the optics at 1000 cm\(^{-1}\) is 3 cm\(^{-1}\). The detector which converts the radiant energy into electrical signals is a germanium lens thermocouple.

The Acculab 8 is equipped with a connector terminal for limited analog/digital output and control. The optical system may be controlled through two lines which start, stop, and reverse the wavelength scan. Four output lines provide both an analog signal from 0 to 1 volts of the transmittance and a wavenumber pulsing signal from the optical system. All logic circuit communication to and from the terminal is in standard transistor-transistor logic (TTL). This terminal supplies enough information and control for data acquisition from the instrument.

Heathkit ET-3400 Trainer Interface

Hardware Description
Input

A Heathkit ET-3400 trainer (25) with an ETA-3400 memory accessory (26) was used in the initial study for data handling and instrument control. The ET-3400 contains a Motorola MC6800 as its central processing unit (CPU). The MC6800 is an eight-bit parallel microprocessor. The trainer provides 512 bytes of memory, but with the addition of an ETA-3400 accessory to the trainer the memory can be expanded to 4096 bytes. The ETA 3400 also provides an RS-232C interface for video terminal connection, a cassette recorder interface for data and program storage, and a Tiny Basic interpreter in ROM for higher level programming.

A programmable parallel input-output communication device (PIO) was used for data acquisition and instrument control in the interface system. The PIO used was the Motorola MC6820 peripheral interface adapter (PIA). A description of PIA operation is given in Appendix A. Thirteen lines of the two eight bit ports of the PIA 1 are employed to collect data through an analog-to-digital (A/D) converter from the spectrophotometer. Attached to each of the thirteen lines is an inverter circuit to convert the output of the A/D to TTL logic. The A/D converter provides a four bit binary coded decimal (BCD) number to PIA 1. This BCD number represents the transmittance from the Acculab 8 which is an analog signal between 0.000 and 1.000 volt. This provides transmittance readings as low as 0.1%. The A/D converter employed in the system was a Systron Donner Model 1234 integrating ramp type converter. A description of the A/D operation and the TTL conversion circuit is also provided in Appendix A.
The control of the interface system is achieved through four lines. Three lines from port A of PIA 1 and one line connected directly to the microprocessor. This is shown in Figure 7a, where the wavenumber scan inhibit (pin 3) and the A/D reset (pin 46) are controlled through lines 8 and 9 of PIA 1 respectively. A description of the switching circuit between line 9 and the A/D reset line is provided in Appendix A. The wavenumber pulse and the order break of the spectrophotometer are connected through a logic circuit to the interrupt request line (IRQ) of the MC6800. This logic circuit provides wavenumber pulsing only when the monochromator is scanning. The wavenumber pulse from the monochromator is also connected to line 7 of PIA 1. This provides the MC6800 microprocessor with the wavenumber position information. Thus, the MC6800 need only take data during the wavenumber range of interest. The chart drive inhibit (pin 4) and the wavenumber reverse (pin 6) lines of the spectrophotometer are connected to common logic ground. This inhibits both lines as they are not used for data acquisition.

Output

After the acquisition of the data from the Acculab 8 spectrophotometer, the derivative was calculated within the MC6800. The derivative was observed using PIA 2 as an output device. Data from PIA 2 was directed to a digital-to-analog (D/A) converter, and subsequently stored in a digital storage oscilloscope. This way spectra were immediately viewed on the oscilloscope screen. A permanent recording of the spectra was later obtained using a X-Y recorder connected to the oscilloscope output. Figure 7b shows the schematic of the hardware connections for
Figure 7a. MC6800 Microprocessor Interface System (Input Hardware)
Figure 7b. MC6800 Microprocessor Interface System (Output Hardware)
the output of the derivative.

A Heath Model EU-800-GC D/A converter (27) was connected to the eight-bit port A of PIA 2. Only eight of the most significant bits of the 10-bit binary resistor ladder D/A converter were connected to PIA 2. The oscilloscope used was a Gould Model OS4000 digital storage oscilloscope (28) with the 4096 byte memory accessory. The oscilloscope is controlled by the microprocessor through port B (line 10) of PIA 2. A high signal on line 10 allows the trigger level of the oscilloscope to be adjusted manually. A low signal on line 10 allows the oscilloscope to receive data from the PIA through the D/A converter. This data is latched in the memory of the oscilloscope. By pressing the memory output of the oscilloscope a recording of the derivative could be obtained on a Princeton Applied Research Model RE0074 X-Y recorder (29).

Software Description

Input

The software for data acquisition and instrument control consists of a Tiny Basic program and four assembly language programs. The central basic program, called "Main Input", interfaces between the assembly language programs and the real world. As seen in Appendix B, Flowchart B-1, "3400 Input", the basic program sets the parameters for data acquisition. These parameters consist of the starting wavenumber of the instrument and the wavenumber range of interest. These are input through the keyboard. The basic program then branches to an assembly language program called "Input Control". This program sets the system for input
and starts the monochromator scan. It also counts the wavenumber pulses from the optical system. Once the beginning of the wavenumber range of interest has been reached, the program executes the Wait For Interrupt instruction.

A high status from the wavenumber pulse to the interrupt request (IRA) line starts data acquisition. The IRA overrides all operations in the microprocessor and starts an interrupt routine. This interrupt routine searches addresses 00FA and 00FB of the RAM and loads their contents into the program pointer. This results in the starting of a new assembly level program called "Take Data". The "Take Data" program resets the A/D converter and acquires eight data points. It then branches to another assembly language program to convert the BCD data to hexadecimal. This subroutine, "BCD Convert", transforms the eight 4-bit data points to their hexadecimal equivalents. Subroutine "BCD Convert" then returns to the interrupt subroutine, "Take Data". After the data points are acquired, the "Take Data" program returns from the interrupt routine to the assembly level program "Input Control". The "Input Control" program checks for the end of the wavenumber range. If the data acquisition is complete, it returns to the basic program "Main Input". If the end of the wavenumber range is not reached, it returns to Wait For Interrupt and continues to take data.

The "Main Input" program branches to another assembly language program to stop the monochromator scan. This program, called "Stop Scan", resets the system to output and inhibits the instrument from scanning. The data points are located between memory positions 0720 to 0DFF. They can then be stored on a cassette recorder or displayed on the
monitor. Listings of all input programs may be found in Appendix B.

**Data Processing**

The data obtained from the infrared spectrophotometer represents the transmittance readings from the wavenumber scan. In order to average data points and calculate the derivative, transmittance values must be converted to absorbance values. The software for the conversion is compiled in Appendix B. The conversion is achieved using a transmittance-absorbance look-up table.

Referring to Appendix B, Flowchart B-2, "3400 Data Processing", the software consists of two assembly language programs and a basic program. The only function of the basic program is to branch to the assembly level program called "Transmittance-Absorbance Conversion" (TAC). This program converts a hexadecimal data point into a 4-bit decimal number. This decimal value depicts the percent transmittance ±0.1 percent. The program then branches to a subroutine called "Set Memory". This subroutine uses the decimal value to fix the corresponding absorbance value in a prestored table. It then returns to "TAC" for data point averaging. After the conversion of the data set is complete, the data is stored on a cassette recorder or displayed on a monitor.

**Output**

The software for outputting the data consists of four programs. As shown in Appendix B, Flowchart B-3, "3400 Output", a basic program accesses three assembly language programs. The first task in the
software is to calculate the first derivative of the absorbance data. This is achieved by branching to an assembly level program called "Derivative". This program calculates the first derivative and stores it in half the memory space needed for the original data. It then branches back to the basic program, "Main Output". This program sets the trigger of the storage oscilloscope for manual level adjustment. Once the trigger level is adjusted manually on the oscilloscope, the basic program branches to a second assembly language program. This program, called "Output Data", outputs the derivative from the PIA through the D/A converter to the memory of the oscilloscope. The derivative can be viewed immediately on the screen of the oscilloscope.

Higher order derivatives are calculated by branching from the basic program to an assembly level program called "Multiderivative". The order of the derivative of interest is entered through the basic program. The program "Multiderivative" then calculates the derivative and returns to the basic program. The basic program then reuses the assembly level program "Output Data" to send the derivative to the oscilloscope. This loop continues until the operator enters a stop code of 10 for the order of derivative. Listings of the output programs are contained in Appendix B.

Apple/Isaac Interface

Hardware Description

Input

A second interface system was developed in order to acquire data
from the infrared spectrophotometer. This system included the Apple II (30) as the microcomputer. The Apple II contains an eight-bit MOS Technology MCS6502 as its central processing unit. The MCS6502 is the most commonly used microprocessor of MOS Technology's 6500 series. The microcomputer system provides 48 kilobytes of RAM with an onboard basic interpreter called Applesoft. Two floppy disk drives were also connected to the Apple II. This provided data and program storage and retrieval. The disk drives expand the storage capabilities by 90 kilobytes. An 80-column Epson MX-80 parallel printer and a high resolution monochrome monitor were also employed for data printout and review.

The hardware for the interface system is that provided in the Cyborg Inc. Isaac 91A unit (31). This universal interface system contains all the electronic devices to achieve a computer interface to most real world devices. Contained within the Isaac are analog I/O, binary I/O, counter, and trigger devices. All these devices are controlled through software stored in the Apple II. This software is an extension of the resident Applesoft basic interpreter and is called Cyborg Inc. Labsoft (32). Labsoft takes up 8 kilobytes in the Apple II RAM.

As shown in Figure 8, to collect the data from the spectrophotometer I/O terminal, one of the sixteen 12-bit A/D converters in the Isaac unit was utilized. The A/D converters are successive approximation types. Three of the four binary resistor ladder D/A converters are connected to the Acculab 8 for instrument control. The "Counterin 2" of the Isaac unit is connected as an input from the order
Figure 8. Apple/Isaac Interface System
break, line 8 of the spectrophotometer. Line 7, the wavenumber pulse of the Acculab 8 I/O terminal is connected to the "Counterin 1" of the Isaac unit for determining the optical system status. These counters are an externally clocked TTL up-counters. All these electronic devices are controlled by a basic program which utilizes the Labsoft interpreter.

Output

The output of the data involves the monitor and printer, which are already part of the Apple II system. The software to utilize these peripheral devices is described in the Output section in the Software Description.

Software Description

Input

Data acquisition and instrument control were achieved with one basic program. This program is called "Apple Input." "Apple Input" uses the Labsoft basic commands to control the Isaac unit for I/O operation. The ampersand (&) which precedes all Labsoft commands is the Applesoft's expansion character. When the Applesoft interpreter encounters the ampersand, it branches to the Labsoft interpreter for proper operation direction. A listing of "Apple Input" program is located in Appendix C.

The "Apple Input" program sets the parameters for data acquisition. Referring to Appendix C, Flowchart C-1, "Apple/Isaac Input", the program then sets the instrument control lines to acquire data through the D/A converter. The optical system status is monitored by
the program through the "Counterin". This provides for data acquisition in the wavenumber range of interest. The data is acquired using a subroutine called "Acquire". In the subroutine, each data point is an average of ten data points. This is achieved by converting the transmittance data to absorbance during data acquisition. An average of the absorbance values is calculated immediately. The absorbance data is then stored by the "Apple Input" program on a disk for further analysis.

Output

The output and processing of the data is achieved through a basic program called "Data Analyzer". This program first loads the data from the disk drive. Data smoothing is provided in the program using the boxcar method. In this technique, a data point value is calculated based on the average of itself with two subsequent data point values. This data smoothing technique significantly decreases the noise in the data. After the data smoothing option, the program displays the wavenumber range of interest on the monitor. A copy of the absorbance values can then be produced on the printer complete with their corresponding wavenumber values.

The "Data Analyzer" program calculates any order derivative desired. An input from the keyboard of zero for the derivative order terminates the program. Once the derivative is calculated, it is displayed on the monitor and subsequently printed. Appendix C contains Flowchart C-2, "Data Analyzer" and a listing of the program.
Systems Comparison

The Apple/Isaac interface system has many advantages over the ET-3400 system. The hardware devices utilized in the connection to the spectrophotometer were essentially equivalent. The Isaac 91A unit's capabilities were not fully utilized in the interface system. A smaller unit, the model 41A, from the manufacture can be configured for the minimal hardware needs that are required.

The major difference in the two interface systems lies in the available memory of the microcomputer units. The Apple/Isaac system provides 20 times the onboard data storage, a faster access to mass storage, and a higher level programming language.
CHAPTER III

EXPERIMENTAL

Procedure

All data acquisition from the Acculab 8 was taken at the scan speed of 120 cm\(^{-1}\)/minute. The optics of the spectrophotometer were set in the order break to start all scans at 2000 cm\(^{-1}\). The wavenumber range of interest was entered as 1750 to 1550 cm\(^{-1}\). This range sufficiently covers the carbon-carbon band at 1654 cm\(^{-1}\). A sodium chloride sample cell was used in the sample beam with a one millimeter cell path thickness. This cell was polished before each day of analysis. Each sample was scanned three times.

At the beginning of each day, the instrument's optical system was checked by scanning a polystyrene film versus air within the wavenumber range of interest. The 100 percent transmittance was set and the scan was taken. The data was checked immediately for the band at 1601.8 cm\(^{-1}\). In all cases, the band was found to be within the instrument's wavenumber resolution of 3 cm\(^{-1}\). Before the sample were scanned, the Acculab 8 was set at 2000 cm\(^{-1}\). A blocking attenuator was used in the reference beam, while the sample cell was placed in the sample beam. The 100 percent transmittance was then set using the blocking attenuator. Between sample analysis, a cell cleaning procedure was followed. First, the cell was rinsed three times with chloroform. It was then dried.
with a stream of dry nitrogen and rinsed several times with the next sample solution. Finally, the cell was filled with the sample and tightly capped. The outside of the cell was rinsed with chloroform and dried with nitrogen to remove all residual sample. Chloroform was used as a cleaning agent because it exhibits no absorbance bands in the wavenumber range of interest.

**Chromophore Study I**

The first study to utilize the computerized infrared spectrophotometer involved standard solutions containing the two chromophores of interest. 1-Hexene was used to simulate the carbon-carbon band found in an oil's spectrum at 1654 cm\(^{-1}\). The 1-hexene absorbance maximum is at 1640 cm\(^{-1}\). 2-Butanone was used to produce the carbon-oxygen band at 1750 cm\(^{-1}\). Mixtures of these standards were prepared and analyzed. The concentration range of the 1-hexene was adjusted so that the intensity of the band produced simulated the carbon-carbon band intensities of some common oils. The range was between 0.05 and 0.25 milliliters of 1-hexene per milliliter of 2-butanone.

The purpose of this study was to determine which derivative maxima to use for the best quantitative results. This was achieved by performing linear least squares analysis on the plot of concentration of the 1-hexene versus the peak height of each derivative maxima. A list of these values is found in Table 2. Each peak height is the average of three sample scans.

Within each derivative, comparing the slopes of the analysis gives an indication of which maxima to use for quantitation. The maximum with
Table 2

Selected Derivative Spectral Values as a Function of C=C Chromophore Concentration

<table>
<thead>
<tr>
<th>C=C (mL/mL sol)</th>
<th>Abs</th>
<th>dA(S₁)/dv</th>
<th>dA(S₂)/dv</th>
<th>dA(S₃)/dv</th>
<th>d²A(S₂)/dv²</th>
<th>d²A(S₃)/dv²</th>
<th>d²A(S₄)/dv²</th>
<th>d³A(S₁)/dv³</th>
<th>d³A(S₂)/dv³</th>
<th>d³A(S₃)/dv³</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.050</td>
<td>0.133</td>
<td>0.0262</td>
<td>0.0683</td>
<td>0.0472</td>
<td>0.0302</td>
<td>0.0075</td>
<td>0.0305</td>
<td>0.0344</td>
<td>0.0215</td>
<td>0.0261</td>
</tr>
<tr>
<td>0.100</td>
<td>0.301</td>
<td>0.0333</td>
<td>0.104</td>
<td>0.0571</td>
<td>0.0429</td>
<td>0.0173</td>
<td>0.0353</td>
<td>0.0417</td>
<td>0.0381</td>
<td>0.0323</td>
</tr>
<tr>
<td>0.150</td>
<td>0.401</td>
<td>0.0328</td>
<td>0.125</td>
<td>0.0669</td>
<td>0.0453</td>
<td>0.0239</td>
<td>0.0416</td>
<td>0.0373</td>
<td>0.0328</td>
<td>0.0357</td>
</tr>
<tr>
<td>0.200</td>
<td>0.486</td>
<td>0.0371</td>
<td>0.150</td>
<td>0.0754</td>
<td>0.0485</td>
<td>0.0218</td>
<td>0.0451</td>
<td>0.0375</td>
<td>0.0371</td>
<td>0.0374</td>
</tr>
<tr>
<td>0.250</td>
<td>0.539</td>
<td>0.0395</td>
<td>0.168</td>
<td>0.0779</td>
<td>0.0476</td>
<td>0.0176</td>
<td>0.0526</td>
<td>0.0459</td>
<td>0.0414</td>
<td>0.0420</td>
</tr>
</tbody>
</table>

| C.C.*           | 0.978 | 0.950     | 0.992      | 0.982      | 0.860       | 0.618       | 0.995       | 0.662       | 0.794       | 0.982       |
| Y-Int           | 0.073 | 0.0266    | 0.049      | 0.0410     | 0.0308      | 0.0103      | 0.0248      | 0.0337      | 0.0225      | 0.0236      |
| Slope           | 1.99  | 0.06      | 0.49       | 0.16       | 0.08        | 0.05        | 0.11        | 0.04        | 0.08        | 0.07        |

* C.C = Correlation Coefficient
the greatest slope response should give the best quantitation. As shown in Table 2, the first derivative maximum with the greatest slope response is \(S_2\). The degree of increase in slope response for maxima \(S_2\) as compared to \(S_1\) and \(S_3\) can best be visualized in the plot shown in Figure 9. With reference to Table 2, the second derivative maximum with the larger slope response is \(S_4\); yet maxima \(S_2\) slope value is not significantly smaller. Both maxima could be used for quantitation. The two maxima of the third derivative with the greatest slope response are \(S_2\) and \(S_3\). Maximum \(S_2\) is not particularly linear with respect to the ethylene concentration, as was evidenced by the correlation coefficient of the least squares analysis. Thus, the maxima of interest for further quantitative analysis studies are: first derivative \(S_2\), second derivative \(S_2\) and \(S_4\), and third derivative \(S_3\).

**Chromopore Study II**

The second study also involved standard solutions for simulation. In order to simulate the fatty acids of the oil more closely, n-butyl acetate was used as the standard for the carbon-oxygen band. This compound contains the ester group common to all oils. A longer chain alkene was also used to produce the carbon-carbon band of the oils at exactly 1654 cm\(^{-1}\). The alkene used in this study was cyclooctene. The purpose of this investigation was to determine the relative independence of the quantitative derivative measurements from the concentration of the carbon-oxygen band. Ratios of the two standards were mixed. Four standard sets were prepared. In each standard set, the
Figure 9. Plot of Concentration of 1-Hexene vs. First Derivative Maxima Values
volume of cyclooctene was varied from 1.0 to 2.5 milliliters while the volume of n-butyl acetate remained constant. The volume of the acetate for the four standard sets (1 through 4) were 8.0, 10.0, 12.0, and 14.0 milliliters, respectively. To assure the two liquids were additive, 20 milliliters of n-butyl acetate were pipetted into a 25 milliliter volumetric flask. Cyclooctene was added from a buret with mixing until the flask was full. The amount of cyclooctene added to the flask was found to be 4.95±0.05 milliliters. This error of 1.0% in the volume was not considered to be significant in these studies. Thus, within each standard set, the concentration of the acetate varies slightly over the cyclooctene range but the relative intensity of the band remains the same.

A linear least squares analysis was performed on the data from the plot of the concentration of cyclooctene versus the derivative maxima values. The resulting slopes from the analysis are compiled in Table 3. The variation in the slopes over the four standard sets represents the dependency of each derivative maxima value on the slope of the ester band. This variation is the percent mean deviation of the slopes contained in Table 3. The first derivative maximum ($S_2$) is the least affected by the ester concentration variation of butyl acetate. However, the second derivative maximum ($S_4$) and the third derivative maximum ($S_3$) seem to have been effected significantly by the ester concentration. This may not be entirely true since a marked loss in precision for higher derivatives may be obscuring the real trends. Nevertheless, this deviation in their slope could cause a large uncertainty in quantitative analysis. The mean deviations of
Table 3
Slope Values from the Least Squares Analysis of Concentration of C=C Chromophore vs. Selective Derivative Values

<table>
<thead>
<tr>
<th>Standard Sample</th>
<th>mL C=C</th>
<th>mL COOR</th>
<th>Abs</th>
<th>$\frac{dA(S_2)}{dv}$</th>
<th>$\frac{d^2A(S_2)}{dv^2}$</th>
<th>$\frac{d^3A(S_2)}{dv^3}$</th>
<th>$\frac{dA(S_4)}{dv}$</th>
<th>$\frac{d^2A(S_4)}{dv^2}$</th>
<th>$\frac{d^3A(S_4)}{dv^3}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Set #</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.0/8.0</td>
<td>0.330</td>
<td>0.121</td>
<td>0.076</td>
<td>0.016</td>
<td>0.050</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.5/8.0</td>
<td>(12.4)</td>
<td>(2.3)</td>
<td>(9.4)</td>
<td>(24.0)</td>
<td>(17.5)</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.0/8.0</td>
<td>0.412</td>
<td>0.106</td>
<td>0.092</td>
<td>0.029</td>
<td>0.070</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.5/8.0</td>
<td>(19.5)</td>
<td>(4.9)</td>
<td>(22.3)</td>
<td>(17.1)</td>
<td>(26.1)</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td></td>
<td></td>
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<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.0/10.0</td>
<td>0.437</td>
<td>0.109</td>
<td>0.106</td>
<td>0.048</td>
<td>0.075</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.5/10.0</td>
<td>(9.4)</td>
<td>(2.7)</td>
<td>(17.6)</td>
<td>(6.9)</td>
<td>(45.0)</td>
<td></td>
<td></td>
<td></td>
<td></td>
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<tr>
<td>2.0/10.0</td>
<td>0.359</td>
<td>0.113</td>
<td>0.092</td>
<td>0.045</td>
<td>0.125</td>
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<td></td>
<td></td>
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<tr>
<td>2.5/10.0</td>
<td>(16.5)</td>
<td>(10.8)</td>
<td>(20.5)</td>
<td>(19.8)</td>
<td>(19.8)</td>
<td></td>
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</tr>
<tr>
<td>1.0/12.0</td>
<td>0.412</td>
<td>0.106</td>
<td>0.092</td>
<td>0.029</td>
<td>0.070</td>
<td></td>
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</tr>
<tr>
<td>1.5/12.0</td>
<td>(12.4)</td>
<td>(2.3)</td>
<td>(9.4)</td>
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<td></td>
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<td>2.0/12.0</td>
<td>0.437</td>
<td>0.109</td>
<td>0.106</td>
<td>0.048</td>
<td>0.075</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.5/12.0</td>
<td>(19.5)</td>
<td>(4.9)</td>
<td>(22.3)</td>
<td>(17.1)</td>
<td>(26.1)</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
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<td></td>
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<td></td>
<td></td>
</tr>
<tr>
<td>1.0/14.0</td>
<td>0.359</td>
<td>0.113</td>
<td>0.092</td>
<td>0.045</td>
<td>0.125</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.5/14.0</td>
<td>(16.5)</td>
<td>(10.8)</td>
<td>(20.5)</td>
<td>(19.8)</td>
<td>(19.8)</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.0/14.0</td>
<td>0.330</td>
<td>0.121</td>
<td>0.076</td>
<td>0.016</td>
<td>0.050</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.5/14.0</td>
<td>(12.4)</td>
<td>(2.3)</td>
<td>(9.4)</td>
<td>(24.0)</td>
<td>(17.5)</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

% Mean Deviation of Slopes

| % Mean Deviation of Slopes | 10.4 | 4.2 | 8.5 | 34.8 | 28.1 |

Average Coefficient of Variation (CV)

| Average Coefficient of Variation (CV) | 14.4 | 5.2 | 17.4 | 17.0 | 27.1 |
the slopes for the absorbance peak height and the second derivative maxima ($S_2$) are each approximately twice the first derivative maxima ($S_2$) value. The first derivative would therefore be preferred in order to better accomplish quantitation of the carbon-carbon band.

The coefficients of variation (34) for the slopes in Table 3 is an indication of data scatter. The average coefficient of variation (CV) over the four standard sets is also listed in Table 3. This value shows an increase with increasing order of derivative which suggests that data scatter from the noise within the spectrophotometer is amplified as higher order derivatives are produced. Interestingly, the CV for the first derivative maximum ($S_2$) is significantly smaller than the CV for the standard base-line method employed on the absorbance peak. This is probably due to the uncertainty in establishing a reproducible base line in the absorbance mode.

**Selected Oil Study**

Six common unsaturated oils were purchased from local food retailers and subsequently studied. They were soybean, corn, olive, sunflower, safflower, and peanut oil. Each oil was scanned three times as a neat liquid. The determination of the iodine numbers of the oils were calculated based on Beer's Law relationship.

$$\frac{A_{\text{std}}}{C_{\text{std}}} = \frac{A_{\text{unk}}}{C_{\text{unk}}}$$  \hspace{1cm} (4)

where std = standard and unk = unknown. Also c = iodine number and A = derivative maxima value. All iodine numbers were based on a soybean oil as a standard sample. The oils were also analyzed by the Hanus
titration method (33). Experimentally determined iodine numbers of
the selected oils are listed in Table 4. Each iodine value determined
spectroscopically is the average from the three separate scans. Also
contained within the tables are the pooled standard deviation (34) and
the coefficient of variation for each derivative maximum studied.

As shown in Table 4, most of the spectroscopically determined
iodine numbers fall within the accepted range of literature values,
with the exception of olive oil. The olive oil iodine values were
significantly high. In order to determine if the original olive oil
was adulterated, a second olive oil sample produced by Fisher Chemical
Company was analyzed. Again, the spectroscopically determined iodine
numbers of the olive oil were still significantly higher than the
accepted range. This implies that the technique was at fault and the
original olive oil was not adulterated.

The probable cause for positively biased iodine numbers for
olive oil may be due to the effect of the band shape resulting from
overlapping bands of significantly different intensities. Figure 2
depicts two overlapping bands, which are significantly different in
intensities. This situation is analogous to the spectrum encountered
with oils where a very intense ester band (A in Figure 2) overlaps a
very much weaker ethylene band (B in Figure 2). Since the spectral
derivatives are dependent on the slope of the original spectra, hope-
fully some region of the spectrum (c to d in Figure 2) of the mixture
may be found which is significantly dependent on the weaker component.
Nevertheless, the degree of dependence will necessarily be a function
of the ratio of the intensities of the major band (ester) to the minor
Table 4

Iodine Numbers of Selected Oils

<table>
<thead>
<tr>
<th>Oil Name</th>
<th>Accepted Iodine Number Range(*)</th>
<th>Iodine Number ± Standard Deviation</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Abs.</td>
</tr>
<tr>
<td>Soybean (std.)</td>
<td>122-134</td>
<td>128</td>
</tr>
<tr>
<td>Corn</td>
<td>111-128</td>
<td>120±7</td>
</tr>
<tr>
<td>Olive</td>
<td>79-88</td>
<td>108±5</td>
</tr>
<tr>
<td>Sunflower</td>
<td>122-134</td>
<td>126±7</td>
</tr>
<tr>
<td>Safflower</td>
<td>135-155</td>
<td>139±2</td>
</tr>
<tr>
<td>Olive (Fisher)</td>
<td>79-88</td>
<td>107±4</td>
</tr>
<tr>
<td><strong>Standard Deviation</strong></td>
<td></td>
<td>1.58</td>
</tr>
<tr>
<td><strong>Coefficient of Variation (CV)</strong></td>
<td></td>
<td>1.32</td>
</tr>
</tbody>
</table>

*Reference 18
band (ethylene). In the case of olive oil, this ratio, due to the lower degree of unsaturation, is significantly larger than the corresponding ratio for soybean oil which was used as the standard. Thus it follows that the best results will be obtained when a standard is selected such that its ratio more nearly approximates that of the sample. Another way of stating this is to say that the iodine number of the standard should be close to that of the sample. The validity of this argument is shown to be true in Table 5. The iodine number of peanut oil was determined using olive oil as the standard. Considering the standard deviations, all the iodine values of the peanut oil agree with the accepted literature range.

The iodine numbers determined by the derivative spectroscopic method tend to exhibit a high bias as compared to the titration method. The derivative maxima that best approximates values obtained by the titration method of all the oils is the first derivative maximum ($S_2$). This maximum also exhibits satisfactory precision as can be seen from the coefficient of variation in Table 4. The CV indicates the precision of the technique employed. The first derivative's CV exhibits the lowest value and thus suggests that the iodine number determined by the maximum ($S_2$) of the first derivative provides the best precision and consequently should be the maxima of choice.
<table>
<thead>
<tr>
<th>Oil Name</th>
<th>Accepted Iodine Number Range (*)</th>
<th>Iodine Number ± Standard Deviation</th>
<th>Hanus Titration</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Abs.</td>
<td>(\frac{dA(S_2)}{d\nu})</td>
</tr>
<tr>
<td>Olive (std.)</td>
<td>79-88</td>
<td>78</td>
<td>78</td>
</tr>
<tr>
<td>Peanut</td>
<td>88-98</td>
<td>79±2</td>
<td>96±3</td>
</tr>
</tbody>
</table>

*Reference 18
CHAPTER IV

DISCUSSION

Advantages and Disadvantages

The main advantage of derivative infrared spectroscopy lies in the increased quantitative capabilities it provides relative to the standard quantitative techniques employed with infrared spectroscopy. The infrared region has always been very useful for qualitative analysis. However, its utilization for quantitative analyses enhances its power. In this investigation, it was shown that quantitation of iodine numbers of oils was accomplished quickly and accurately with the derivative technique. Many of the problems encountered in the standard titration method for determining iodine numbers are eliminated in the spectroscopic method. The typical analysis time for the computerized derivative infrared technique is approximately 2 minutes. This decreases the analysis time of the standard titration method used by food technologists by approximately 15 fold.

As a result of this investigation, it was found that the derivative technique is limited by the noise within the spectrophotometer. The inherent noise in the Acculab 8 infrared instrument limits the usefulness of the quantitative derivative technique to the first derivative. If higher signal-to-noise ratios could be achieved, as with Fourier Infrared Spectroscopy, higher order derivatives would
likely eliminate the problem of the choice of appropriate standard oils encountered in this study.

Conclusion

The infrared derivative spectroscopic technique provides a quantitative method that closely approximates the accepted method. The quantitative derivative method provides data with a relative error of about 1 percent. This technique permits quantitation in the infrared region at approximately the same level of precision and accuracy as the more elaborate computerized base-line correction methods.

This technique should be applicable to any compound or compounds containing measurable amounts of unsaturation. A good application would be in the agricultural area to measure total unsaturation of food products. Another industry involving unsaturation measurements would be the petroleum and allied industries. Many in-process checks involving unsaturation of the products can be accomplished quickly and accurately by employing the derivative I.R. technique.

Recommendations

The construction of the interface system used in these studies was built as a matter of convenience. A commercially built unit would likely use the optimum amount of hardware consistent with the quality of spectrophotometer employed. The best system might contain, within the instrument, a microprocessor instead of a full microcomputer. All the programming needed to control the instrument and to acquire and process data would be resident as firmware in the system. The minimum
RAM needed to acquire data over the full spectral range would be approximately 16 kilobytes (8 bit). The data acquisition hardware would be comparable to that found in the ET-3400 interface system. The cost of such a spectrophotometer interface system would be significantly lower than the Apple/Isaac system employed in this study.
APPENDIX A

Peripheral Interface Adapter (PIA) Operation

The Motorola 6820 peripheral interface adapter (PIA) (35,36) has two input/output (I/O) ports each possessing three independent registers. These registers are shown in Figure A-1. They are referred to as: the output registers (ORA and ORB), the data direction registers (DDRA and DDRB), and the control registers (CRA and CRB). These six registers are each individually addressable by the microprocessor unit (MPU). The A and B indicate the two different ports of the PIA. The PIA provides two parallel eight-bit ports (A and B) which can be programmed as either an input, output, or special function port.

Figure A-2 shows a diagram of the MPU system interfaced with the PIA. The MPU side of the total system includes three chip select lines CS0, CS1, and CS2 for selecting a particular PIA. These lines, along with two register select lines, RS0 and RSI, are connected to the address bus of the MPU. RS0 and RSI are used in conjunction with four interrupt control bits, CA1, CA2, CB1, and CB2 to address the six registers within the PIA. The four interrupt lines are held at a high state in the interface by connecting each to the five volt supply through a one thousand ohm resistor. This is to prohibit any outside interruption of these lines which would alter the PIA function. The read/write (R/W) and reset (RES) lines of the PIA are connected to the same corresponding lines of the MPU. The enable line of the PIA is pulsed by the 02 clock signal of the MPU. Lines IRQA and IRQB
Address

8000  |  Output Register A (ORA)
Side A

8001  |  Data Direction Register A (DDRA)

8001  |  Control Register A (CRA)

8002  |  Output Register B (ORB)
Side B

8003  |  Data Direction Register B (DDRB)

8003  |  Control Register B (CRB)

Figure A-1. Address Assignments of PIA Registers

Figure A-2. PIA Interface
are interrupt request lines for each side of the PIA. These lines are connected to the respective \( \overline{IRQ} \) line of the MPU.

The logic scheme for addressing the PIA is shown in Figure A-3(a). Address memory locations 8000 to 8003 represent the two sets of independent register ports. These addresses on the MPU's address bus initialize the chip select lines CS0, CS1, and CS2. The two register select lines RSO and RS1 are connected to the last two significant bits of the address bus. Thus, addresses 8000 and 8001 control port A of the PIA; while addresses 8002 and 8003 control port B of the PIA.

Figure A-3(b) shows the logic circuit that enables the data input/output bus. When the valid memory address (VMA), the address line 15 (A15), the control select lines, CS0 and CS1, and the R/W lines are all high status, the NAND gate enables the read enable line (\( \overline{RE} \)). Once the \( \overline{RE} \) line is enabled, the tristate data bus from the PIA to the MPU is opened which makes data transfer possible.

Referring to Figure A-3(a), the two register select lines, RSO and RS1, control the operation of the PIA. Line RS1 selects which port, A or B, of the PIA will be addressed. A high status on RS1 selects port B, while a low status on RS1 selects port A. Line RSO selects which register is affected by the MPU. When RSO is at high status, the CRA or CRB is selected. A low status on line RSO selects the DDRA or DDRB.

To initialize the PIA, the MPU must first set the control register to either output or input. An address of 8001 on the address bus sets the RS1 line at low status. This selects A port of the PIA and sets RSO at high status, thus initializing the CRA. Bit number 2 of the
(a) Addressing of PIA Decoding

VMA
A15 (1)
A14
A13 (0)
A12 (0)
A1 (0)
A0 (0)

Pin 35
Pin 36

RS1
(0)
RS0

chooses A or B side

P I A

A15
VMA
(1)
(0) Pin 23

CS2

A14 (0)
A13 (0)
A12 (0)
A1 (0)
A0 (0)

Pin 35
Pin 36

CS1

(b) Data Input/Output Decoding

VMA
A15 (1)
A14
A13 (0)
A12 (0)
A1 (0)
A0 (0)

(0)

Data I/O on MPU

Logic (0) at Data I/O activates I/O port

R/W (1)

Figure A-3. Addressing to PIA

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CRA is the control bit for the selection of input or output for port A. Bit number 2 is at high status by loading the hexadecimal number 04 into memory location 8001. This selects the DDRA as an input register. The data in the DDRA is located at memory location 8000. The MPU only needs to read memory location 8000 to receive the data. For the MPU to output data, the ORA has to be initialized. This is done by setting bit number 2 of the CRA to low status by loading 00 into memory location 8001. The MPU can now output data by writing data into memory location 8000. The PIA essentially becomes four memory locations for data transfer in and out of the MPU.

Analog-to-Digital Converter Operation
(Systron Donnor Model 1234)

Model 1234 analog-to-digital (A/D) converter (37) is an integrating ramp type converter. The converter contains five major electronic components. These are a voltage ramp generator, two voltage comparators, a crystal oscillator, and a counter. The voltage generator consists of a current source and an operational amplifier in the integrator configuration. The generator provides a linearly decreasing voltage ramp from +12 to -12 volts. Referring to the schematic of the converter in Figure A-4, the operation of the converter starts with a high status at the reset line. This signals the voltage ramp generator to start and also resets the counter to zero. The ramp voltage is connected to the inputs of the two comparators. The ramp voltage is compared to zero volts by comparator (1) and to the input voltage through comparator (2). At the time the ramp voltage is equal to zero a pulse is generated at the output of comparator (1). This output
Figure A-4. Model 1234 Analog-to-Digital Converter
gates the crystal oscillator to the counter. The counter continues to count the oscillations until a negative signal occurs at the input of comparator (2). This is caused when the voltage ramp reaches the negative value of the input voltage. The digital value, a four bit BCD number in the counter, is proportional to the analog input voltage.

**TTL Conversion Circuit Operation**

The output of the Model 1234 A/D converter is not TTL compatible. To accommodate this, the electrical circuit shown in Figure A-5 was constructed. One of these conversion circuits was connected to each of the thirteen lines between the A/D converter and the PIA. The device consisted of an inverter, a diode, and a 1 megohm resistor. When a "logic 1" from the A/D converter (-15 volts) is input, the diode conducts to ground. This connects the input of the inverter to ground also. This causes the output of the inverter to have a high TTL status of

![Figure A-5. TTL Conversion Circuit](image-url)
approximately 3.4 volts. A "logic 0" (0 volts) from the A/D converter prevents the diode from conducting. This allows the +5 volts source to float the input of the inverter to +5 volts causing a low TTL status, zero volts, at the input of the inverter.

Reset Switch Operation

The switch (38) used between the PIA and the reset line of the A/D converter is illustrated in Figure A-6. It consists of a PNP type transistor, which functions as a switch; ans three 10 kilohm resistors. An input from the PIA of zero volts opens the base of the transistor. This drains the -15 volt source across the transistor and provides an output to the reset line of zero volts. To reset the A/D converter the PIA outputs a high status of +5 volts. This closes the base of

---

Figure A-6. Reset Switch Circuit
the transistor and opens the -15 volt source to the reset line.
Appendix B
Flowchart B-1. 3400 Input
Flowchart B-1 cont.
"Main Input" (Tiny Basic)

10 PRINT "INPUT STARTING WAVENUMBER OF SCAN IN CM^-1"
15 PRINT "INPUT WILL BE 4000 CM^-1 OR 2000 CM^-1"
20 INPUT A
30 PRINT "INPUT WAVENUMBER RANGE TO BE STUDIED IN CM^-1"
40 PRINT "WAVENUMBER (MAX.)"
50 INPUT B
60 PRINT "WAVENUMBER (MIN.)"
70 INPUT C
80 PRINT "MAKE SURE THE I.R. IS SET AT",A,"CM^-1"
90 PRINT "THE AREA TO BE RECORDED IS BETWEEN"
100 PRINT B,"CM^-1 AND",C,"CM^-1"
110 IF A=4000 GOTO 140
120 D=A-B
130 GOTO 150
140 D=(A-B)/2
150 LET G=0
160 IF D<256 GOTO 230
170 D=D-256
180 G=G+1
190 GOTO 160
230 D=USR(7192,0001,D)
240 G=USR(7192,0000,G)
250 IF A=4000 GOTO 230
260 E=B-C
270 GOTO 290
280 E=(B-C)/2
290 LET G=0
300 IF E<256 GOTO 370
310 E=E-256
320 G=G+1
360 GOTO 300
370 E=USR(7192,0003,E)
380 G=USR(7192,0002,G)
385 PRINT "NOW, START THE I.R."
386 PRINT "BY PRESSING THE SCAN BUTTON"
387 J=USR(1680)
388 PRINT "YOU MAY STOP THE SCAN NOW"
400 K=USR(1456)
410 PRINT
420 PRINT "NOW, ENTER NEXT PROGRAM FROM RECORDER"
430 END

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"Input Control" (Assembly)

0690 LDAA 86 07  Load memory locations with
0692 STAA B7 00 04  initialization data.
0695 LDAA 86 20
0697 STAA B7 00 05
069A SEI 0F  Set interrupt mask so wave-
069B LDAA 86 80 00  number pulse does not interrupt.
069E LSRA 44 44 44  Load from PIA wavenumber inhibit
06A1 LSRA 44 44 44 status.
06A4 LSRA 44
06A5 TSTA 4D
06A6 BEQ 27 16  Branch if no wavenumber inhibit.
05A8 NOP 01
06A9 LDAA 86 04
06AB STAA B7 80 01
06AE LDAA B6 80 00
06B1 LDAB C6 40
06B3 SBA 10
06B4 LSRA 44 44 44
06B7 LSRA 44 44
06B9 TSTA 4D
06BA BEQ 27 17  Branch to start scan.
06BC BRA 20 EB
06BE LDAA 86 04
06C0 STAA B7 80 01
06C3 LDAA B6 80 00
06C6 LDAB C6 C0
06C8 SBA 10
06C9 LSRA 44 44 44
06CC LSRA 44 44
06CE TSTA 4D
06CF BEQ 27 02  Branch to start scan.
06D1 BRA 20 EB
06D3 LDAA 86 00
06D5 STAA B7 80 01
06D8 CLI 0E  Clear interrupt mask.
06D9 WAI 3E  Wait for wavenumber pulse
to interrupt, branch to
interrupt subroutine Take Data.
06DA SEI 0F  Check wavenumber range covered.
06DB LDX CE 00 00
06DE CPX BC 00 02
06E1 BEQ 27 02  If spectra range is covered
06E3 BRA 20 F3  return to Tiny Basic.
06E5 RTS 39  If spectra range is not
covered return to wait for
interrupt or wavenumber pulse.

Check wavenumber pulse status.

Branch if no wavenumber inhibit.

Branch to start scan.

Branch to start scan.

Set PIA port A to output.

Clear interrupt mask.

Wait for wavenumber pulse
to interrupt, branch to
interrupt subroutine Take Data.

Check wavenumber range covered.

If spectra range is covered
return to Tiny Basic.

If spectra range is not
covered return to wait for
interrupt or wavenumber pulse.

Return to Main Input program.
## "Take Data" (Assembly)

<table>
<thead>
<tr>
<th>Line No.</th>
<th>Instruction</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0600</td>
<td>LDX CE 00 00</td>
<td>Check wavenumber status.</td>
</tr>
<tr>
<td>0603</td>
<td>CPX BC 00 00</td>
<td>Branch to acquire data.</td>
</tr>
<tr>
<td>0606</td>
<td>BEQ 27 02</td>
<td>Branch to input control.</td>
</tr>
<tr>
<td>0609</td>
<td>LDX CE 00 00</td>
<td>Check wavenumber status.</td>
</tr>
<tr>
<td>060D</td>
<td>CPX BC 00 02</td>
<td>Branch to input control.</td>
</tr>
<tr>
<td>0610</td>
<td>BEQ 27 63</td>
<td>Branch to input control.</td>
</tr>
<tr>
<td>0612</td>
<td>LDX FE 00 02</td>
<td>Set current memory location for data entry.</td>
</tr>
<tr>
<td>0615</td>
<td>DEX 09</td>
<td></td>
</tr>
<tr>
<td>0616</td>
<td>STX FF 00 02</td>
<td>Initialize memory locations.</td>
</tr>
<tr>
<td>0619</td>
<td>CLR 7F 00 0C</td>
<td></td>
</tr>
<tr>
<td>061C</td>
<td>CLR 7F 00 0D</td>
<td></td>
</tr>
<tr>
<td>061F</td>
<td>LDAB CE 08</td>
<td>Set number of data point to be taken.</td>
</tr>
<tr>
<td>0621</td>
<td>STAB F7 00 0E</td>
<td>Set PIA port A to output.</td>
</tr>
<tr>
<td>0624</td>
<td>LDAA 86 00</td>
<td>Set PIA port A to output.</td>
</tr>
<tr>
<td>0626</td>
<td>STAA B7 80 01</td>
<td></td>
</tr>
<tr>
<td>0629</td>
<td>LDAA 86 40</td>
<td>Reset A/D converter.</td>
</tr>
<tr>
<td>062B</td>
<td>STAA B7 80 00</td>
<td></td>
</tr>
<tr>
<td>062E</td>
<td>LDX CE 01 F8</td>
<td></td>
</tr>
<tr>
<td>0631</td>
<td>DEX 09</td>
<td></td>
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<tr>
<td>0632</td>
<td>BNE 26 FD</td>
<td></td>
</tr>
<tr>
<td>0634</td>
<td>LDX FE 00 04</td>
<td></td>
</tr>
<tr>
<td>0637</td>
<td>LDAA 86 00</td>
<td>Reset output status.</td>
</tr>
<tr>
<td>0639</td>
<td>STAA B7 80 00</td>
<td></td>
</tr>
<tr>
<td>063C</td>
<td>LDAA 86 04</td>
<td>Set PIA ports A and B to input.</td>
</tr>
<tr>
<td>063E</td>
<td>STAA B7 80 01</td>
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</tr>
<tr>
<td>0641</td>
<td>STAA B7 80 03</td>
<td></td>
</tr>
<tr>
<td>0644</td>
<td>LDAA B6 80 00</td>
<td>Store A/D converter BCD number.</td>
</tr>
<tr>
<td>0647</td>
<td>STAA A7 00 08</td>
<td></td>
</tr>
<tr>
<td>064A</td>
<td>LDAA B6 80 02</td>
<td></td>
</tr>
<tr>
<td>064D</td>
<td>STAA A7 00 08</td>
<td></td>
</tr>
<tr>
<td>0650</td>
<td>JSR BD 0E 00</td>
<td>Branch to subroutine BCD Convert.</td>
</tr>
<tr>
<td>0653</td>
<td>LDAA B6 00 0E</td>
<td></td>
</tr>
<tr>
<td>0656</td>
<td>DECA 4A</td>
<td>Check number of data points.</td>
</tr>
<tr>
<td>0657</td>
<td>BED 27 05</td>
<td></td>
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<tr>
<td>0659</td>
<td>STAA B7 00 0E</td>
<td></td>
</tr>
<tr>
<td>065C</td>
<td>BRA 20 CE</td>
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</tr>
<tr>
<td>065E</td>
<td>LDX FE 00 04</td>
<td>Store converted data into proper memory location.</td>
</tr>
<tr>
<td>0661</td>
<td>LDAA B6 00 0C</td>
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</tr>
<tr>
<td>0664</td>
<td>STAA A7 00 09</td>
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</tr>
<tr>
<td>0667</td>
<td>LDAA B6 00 0D</td>
<td></td>
</tr>
<tr>
<td>066A</td>
<td>STAA A7 00 08</td>
<td></td>
</tr>
<tr>
<td>066D</td>
<td>STX FF 00 04</td>
<td></td>
</tr>
<tr>
<td>0670</td>
<td>LDAA B6 00 01</td>
<td></td>
</tr>
<tr>
<td>0672</td>
<td>STAA B7 80 01</td>
<td></td>
</tr>
<tr>
<td>0675</td>
<td>LDX CE 78 00</td>
<td>Timer loop for data acquire.</td>
</tr>
<tr>
<td>0678</td>
<td>DEX 09</td>
<td></td>
</tr>
<tr>
<td>0679</td>
<td>BNE 26 FD</td>
<td></td>
</tr>
<tr>
<td>067B</td>
<td>BRA 20 0D</td>
<td></td>
</tr>
</tbody>
</table>

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Timer loop for no data acquire.
Decrement wavenumber status.
Return from interrupt to Input Control program.
**"BCD Convert" (Assembly)**

<table>
<thead>
<tr>
<th>Address</th>
<th>Instruction</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0E00</td>
<td>LDX FE 00 04</td>
<td>Move data to new memory location.</td>
</tr>
<tr>
<td>0E03</td>
<td>STX FF 00 06</td>
<td></td>
</tr>
<tr>
<td>0E06</td>
<td>INT 08</td>
<td></td>
</tr>
<tr>
<td>0E07</td>
<td>STX FF 00 08</td>
<td></td>
</tr>
<tr>
<td>0E0A</td>
<td>NOP 01</td>
<td></td>
</tr>
<tr>
<td>0E0B</td>
<td>CLR 7F 00 0A</td>
<td>Initialize memory locations.</td>
</tr>
<tr>
<td>0E0E</td>
<td>CLR 7F 00 0B</td>
<td></td>
</tr>
<tr>
<td>0E11</td>
<td>LDX FE 00 06</td>
<td>Check status of BCD number bit 4.</td>
</tr>
<tr>
<td>0E14</td>
<td>LDAA A6 00</td>
<td></td>
</tr>
<tr>
<td>0E16</td>
<td>ASLA 48 48 48</td>
<td></td>
</tr>
<tr>
<td>0E19</td>
<td>LSRA 44 44 44</td>
<td></td>
</tr>
<tr>
<td>0E1C</td>
<td>LSRA 44 44 44</td>
<td></td>
</tr>
<tr>
<td>0E1F</td>
<td>LSRA 44</td>
<td></td>
</tr>
<tr>
<td>0E20</td>
<td>TSTA 4D</td>
<td></td>
</tr>
<tr>
<td>0E21</td>
<td>CLC 0C</td>
<td></td>
</tr>
<tr>
<td>0E22</td>
<td>BED 27 07</td>
<td></td>
</tr>
<tr>
<td>0E24</td>
<td>NOP 01</td>
<td></td>
</tr>
<tr>
<td>0E25</td>
<td>LDX CE 03 0B</td>
<td>Add hexadecimal equivalent of BCD bit 4 to memory.</td>
</tr>
<tr>
<td>0E28</td>
<td>STX FF 00 0A</td>
<td></td>
</tr>
<tr>
<td>0E2B</td>
<td>LDX FE 00 06</td>
<td>Check status of BCD number bit 3.</td>
</tr>
<tr>
<td>0E2E</td>
<td>LDAA A5 00</td>
<td></td>
</tr>
<tr>
<td>0E30</td>
<td>ASLA 48 48 48</td>
<td></td>
</tr>
<tr>
<td>0E33</td>
<td>ASLA 48</td>
<td></td>
</tr>
<tr>
<td>0E34</td>
<td>LSRA 44 44 44</td>
<td></td>
</tr>
<tr>
<td>0E37</td>
<td>LSRA 44</td>
<td></td>
</tr>
<tr>
<td>0E38</td>
<td>TSTA 4D</td>
<td></td>
</tr>
<tr>
<td>0E39</td>
<td>CLC 0C</td>
<td></td>
</tr>
<tr>
<td>0E3A</td>
<td>BEQ 27 17</td>
<td></td>
</tr>
<tr>
<td>0E3C</td>
<td>DECA 4A</td>
<td></td>
</tr>
<tr>
<td>0E3D</td>
<td>LDAB C6 04</td>
<td>Add hexadecimal equivalent of BCD bit 3 to memory.</td>
</tr>
<tr>
<td>0E3F</td>
<td>ADDB FB 00 0B</td>
<td></td>
</tr>
<tr>
<td>0E42</td>
<td>STAB F7 00 0B</td>
<td></td>
</tr>
<tr>
<td>0E45</td>
<td>BCS 25 02</td>
<td></td>
</tr>
<tr>
<td>0E47</td>
<td>BRA 20 EF</td>
<td></td>
</tr>
<tr>
<td>0E49</td>
<td>LDAB C6 01</td>
<td></td>
</tr>
<tr>
<td>0E4B</td>
<td>ADDB FB 00 0A</td>
<td></td>
</tr>
<tr>
<td>0E4E</td>
<td>STAB F7 00 0A</td>
<td></td>
</tr>
<tr>
<td>0E51</td>
<td>BRA 20 E5</td>
<td></td>
</tr>
<tr>
<td>0E53</td>
<td>BRA 20 02</td>
<td></td>
</tr>
<tr>
<td>0E55</td>
<td>BRA 20 B7</td>
<td></td>
</tr>
<tr>
<td>0E57</td>
<td>LDX FE 00 08</td>
<td>Check status of BCD number bit 2.</td>
</tr>
<tr>
<td>0E5A</td>
<td>LDAA A6 00</td>
<td></td>
</tr>
<tr>
<td>0E5C</td>
<td>LSRA 44 44 44</td>
<td></td>
</tr>
<tr>
<td>0E5F</td>
<td>LSRA 44</td>
<td></td>
</tr>
<tr>
<td>0E60</td>
<td>TSTA 4D</td>
<td></td>
</tr>
<tr>
<td>0E61</td>
<td>CLC 0C</td>
<td></td>
</tr>
<tr>
<td>0E62</td>
<td>BEQ 27 17</td>
<td></td>
</tr>
<tr>
<td>0E64</td>
<td>DECA 4A</td>
<td></td>
</tr>
<tr>
<td>0E65</td>
<td>LDAB C6 0A</td>
<td>Add hexadecimal equivalent of BCD bit 2 to memory.</td>
</tr>
<tr>
<td>0E67</td>
<td>ADDB FB 00 0B</td>
<td></td>
</tr>
</tbody>
</table>

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Check status of BCD number bit 1.

Add hexadecimal equivalent of BCD bit 1 to memory.

Return to Take Data interrupt subroutine.
"Stop Scan" (Assembly)

05B0  LDA A 86 00  Set PIA port A to output.
05B2  STA A 87 80  01
05B5  LDA A 86 80  Inhibit instrument scan.
05B7  STA A 87 80  00
05BA  RTS 39  Return from subroutine to Tiny Basic program Main Input
Flowchart B-2. 3400 Data Processing
"Data Processor" (Tiny Basic)

10 PRINT "THIS PROGRAM CONVERTS TRANSMITTANCE TO ABSORBANCE"
20 H=USR(1536)
30 PRINT "ENTER NEXT PROGRAM FROM RECORDER"
40 END
"TAC" (Assembly)

Initialize temporary memory for beginning of the data.

Convert binary LSB's of data to decimal percent transmittance equivalent.

Increment temporary memory for LSB larger than 99.

Check if conversion is complete for LSB's.

Convert binary MSB's of data to decimal percent transmittance equivalent.
Odd carry to MSB's from LSB's.

Store decimal percent transmittance in memory.
positions 0F90 through 0F93.

<table>
<thead>
<tr>
<th>Address</th>
<th>Opcode</th>
<th>Assembly</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>06E8</td>
<td>BRA</td>
<td>20 9F</td>
<td>Jump to subroutine Set Memory.</td>
</tr>
<tr>
<td>06EA</td>
<td>JSR</td>
<td>BD 0E 00</td>
<td>Check for end of data.</td>
</tr>
<tr>
<td>06ED</td>
<td>LDX</td>
<td>FE 00 06</td>
<td></td>
</tr>
<tr>
<td>06F0</td>
<td>CPX</td>
<td>BC 00 04</td>
<td></td>
</tr>
<tr>
<td>06F3</td>
<td>BEQ</td>
<td>27 02</td>
<td></td>
</tr>
<tr>
<td>06F5</td>
<td>BRA</td>
<td>20 50</td>
<td>Return from subroutine to</td>
</tr>
<tr>
<td>06F7</td>
<td>RTS</td>
<td>39</td>
<td>Tiny Basic program Data</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Processor.</td>
</tr>
</tbody>
</table>
"Set Memory" (Assembly)

0E00 LDX CE 0F 93 Set bit 1 from tenths position of percent transmittance.
0E03 LDAA A6 00
0E05 LDAB C6 05
0E07 SBA 10
0E08 BMI 2B 33
0E0A LDX CE 0F 92 Set bit 2 from ones position of percent transmittance.
0E0D LDAA A6 00
0E0F LDAB C6 01
0E11 ABA 1B
0E12 STAA B7 0F 92
0E15 LDAB C6 01
0E17 SBA 10
0E18 BEQ 27 02
0E1A BRA 20 27
0E1C CLR 7F 0F 92
0E1F NOP 01 01
0E21 LDX CE 0F 91 Set bit 3 from tens position of percent transmittance.
0E24 LDAA A6 00
0E26 LDAB C6 01
0E28 ABA 1B
0E29 STAA B7 0F 91
0E2C LDAB C6 0A
0E2E SBA 10
0E2F BEQ 27 02
0E31 BRA 20 10
0E33 CLR 7F 0F 91
0E36 NOP 01 01
0E38 LDX CE 0F 90 Set bit 4 from hundreds position of percent transmittance.
0E3B LDAA A6 00
0E3D LDAB C6 01
0E3F ABA 1B
0E40 STAA B7 0F 90
0E43 CLR 7F 00 00
0E46 CLR 7F 00 01
0E49 LDAA B6 0F 90 Count memory positions for bit 1.
0E4C TSTA 4D
0E4D BEQ 27 14
0E4F LDAB C6 64
0E51 ADDB FB 00 01
0E54 STAB F7 00 01
0E57 BCS 25 05
0E59 DECA 4A
0E5A BEQ 27 07
0E5C BRA 20 F1
0E5E INC 7C 00 00
0E61 BRA 20 F6
0E63 LDAA B6 0F 91 Count memory positions for bit 2.
0E66 TSTA 4D
0E67 BEQ 27 14
0E69 LDAB C6 0A
0E6B ADDB FB 00 01
0E6E STAB F7 00 01
0E71 BCS 25 05
0E73 DECA 4A
0E74 BGT 2E 74
0E76 LDAA CG 05
0E78 INC 7C 00 00
0E7B BRA 20 FG
0E7D LDAA B6 0F 92 Count memory positions for bit 3.
0E80 ADDA BB 00 01
0E83 STAA B7 00 01
0E86 BCS 25 02
0E88 BRA 20 03
0E8A INC 7C 00 00
0E8D LDX CE 0F 92
0E90 LDAB E6 00
0E92 LDX CE 0F 91
0E95 LDAA A6 00
0E97 ASLA 48 48 48
0E99 ASLA 48
0E9B ABA IB
0E9C STAA A7 00
0E9E LDAB CE 05
0EA0 LDAA B6 0F 90 Count memory positions for bit 4.
0EA3 SBA 10
0EA4 BGT 2E 74
0EA6 BLT 2D 08
0EA8 LDAB CE 56
0EAA LDAA B6 0F 91 Logic for determining LSB of memory position of look-up table.
0EAD SBA 10
0EAE BGE 2C 6A
0EB0 LDAB CE 03
0EB2 LDAA B6 0F 90
0EB5 SBA 10
0EB6 BGT 2E 5E
0EB8 BLT 2D 08
0EBA LDAB CE 03
0EBC LDAA B6 0F 91
0EBF SBA 10
0EC0 BGE 2C 54
0EC2 LDAB CE 01
0EC4 LDAA B6 0F 90
0EC7 SBA 10
0EC8 BGT 2E 48
0ECA BLT 2D 08
0ECC LDX CE 70 00
0ECF CPX BC 0F 91
0ED2 BMI 2B 3E
0ED4 LDAB CE 01
0ED5 LDAA B6 0F 90
0ED9 SBA 10
0EDA BEQ 27 32
0EDC NOP 01 01
0EDE LDX CE 94 00

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Logic for determining MSB of memory position of look-up table.

Replace MSB of transmittance with absorbance value from look-up table.

Replace LSB of transmittance with absorbance value from look-up table.

Return from subroutine to TAC program.
Flowchart B-3. 3400 Output
"Main Output" (Tiny Basic)

10 PRINT "MAKE SURE YOU HAVE STORED YOUR ORIGINAL DATA"
20 PRINT "BECAUSE THE CALCULATED DATA WRITES OVER THE ORIGINAL DATA"
25 PRINT "IF YOU HAVEN'T THEN ENTER A 0 (ZERO) AFTER THE ? MARK"
26 PRINT "AND RECORD DATA USING THE MONITOR"
30 PRINT "TO CALCULATE FIRST DERIVATIVE OF SPECTRA"
40 PRINT ENTER A 1 (ONE) FOR INPUT AFTER THE ? MARK"
50 INPUT A
55 IF A=0 GOTO 60
53 GOTO 71
60 C=1824
61 D=USR(7188,0005)
62 E=USR(7188,0004)
63 E=E*256
64 E=E+D
65 PRINT "THE DATA IS BETWEEN",C,"AND",E
66 PRINT "REMEMBER THIS IS IN DECIMAL AND THE MONITOR"
67 PRINT "IS IN HEXADECIMAL SO CONVERT"
68 PRINT "AFTER STORING DATA RESTART THIS PROGRAM BY"
69 PRINT "PRESSING THE B ON THE KEYBOARD AND TYPING RUN"
70 B=USR(5120)
71 B=USR(3696)
80 L=(E-C)/2
90 PRINT "THE OUTPUT PROGRAM TAKES UP 55 USEC"
100 PRINT "YOUR DATA TAKES UP",L,"LOCATIONS IN MEMORY"
110 PRINT "MULTIPLY THESE TWO NUMBERS AND ADJUST THE TIME"
120 PRINT "ON THE O-SCOPE TO COORDINATE"
130 PRINT "NOW ADJUST THE TRIGGER LEVEL ON THE O-SCOPE"
140 PRINT "SO THAT THE L.E.D. LIGHTS UP"
150 F=0
160 F=USR(7192,32763,F)
170 F=USR(7192,32771,F)
180 G=1
190 G=USR(7192,32770,G)
200 PRINT
210 PRINT "NOW TO DISPLAY THE DERIVATIVE IN THE NUMBER",A,"ORDER"
220 PRINT "INPUT A 1 (ONE) AFTER THE ? MARK"
230 INPUT Y
235 J=USR(3584)
240 PRINT "IF THE DISPLAY DOESN'T LOOK RIGHT ENTER A 1 AFTER THE ? MARK"
250 PRINT "IF THE DISPLAY IS RIGHT ENTER A 2 AFTER THE ? MARK"
260 INPUT Z
270 IF Z=1 GOTO 30
280 PRINT "ENTER NEXT ORDER, IF DESIRED, OF DERIVATIVE"
290 PRINT "ENTER A 10 IF YOU WISH TO STOP"
295 INPUT A
296  L=L-1
300  IF  A=10  GOTO  400
310  K=USR(3632)
320  GOTO  90
400  END
"Output Data" (Assembly)

- **0E00** LDAA 86 00  
  - Set PIA port B to output.
- **0E02** STAA B7 80 03  
- **0E05** NOP 01  
- **0E06** LDAA 86 00  
  - Set PIA port A to output.
- **0E08** STAA B7 80 01  
- **0E0B** LDX CE 07 20  
  - Load first memory position of data.
- **0E0E** STX FF 00 00  
  - Trigger oscilloscope to receive data.
- **0E11** LDAA 86 00  
- **0E13** STAA B7 80 02  
  - Send data to oscilloscope.
- **0E16** LDX FE 00 00  
- **0E19** LDAA A6 00  
- **0E1B** STAA B7 80 00  
- **0E1E** INX 08  
- **0E1F** STX FF 00 00  
- **0E22** DEX 09  
- **0E23** CPX BC 00 04  
  - Check for end of data.
- **0E26** BEQ 27 04  
- **0E28** NOP 01 01  
- **0E2A** BRA 20 EA  
  - Return from subroutine to Tiny Basic program Main Output.
"Derivative" (Assembly)

0E70 LDX CE 07 21 Initialize temporary memory
0E73 STX FF 00 02 for the beginning of the
0E76 LDX CE 07 20 data.
0E79 STX FF 00 00
0E7C LDX CE 07 23
0E7F STX FF 00 08
0EB2 LDX CE 07 22
0EB5 STX FF 00 06
0EB8 LDX FE 00 02 Load LSB of Nth. data point.
0EBB LDA A6 00
0EBD LDX FE 00 08 Load LSB of Nth.+1 data point.
0E90 SUBA A0 00
0E92 STAA B7 00 0F Subtract LSB’s of data points.
0E95 LDX FE 00 00 Load MSB of Nth. data point.
0E98 LDA A6 00
0E9A LDX FE 00 06 Load MSB of Nth.+1 data point.
0E9D SBCA A2 00 Subtract MSB’s of data points.
0E9F STAA B7 00 0E
0EA2 CLC 0C
0EA3 LDA A6 00 0E
0EA6 LDX FE 00 00
0EA9 STA A7 00
0EAB LDA A6 00 0F
0EAE LDX FE 00 02
0EB1 STA A7 00
0EB3 LDX FE 00 00 Advance temporary memory
0EB6 INX 08 08 positions.
0EB8 STX FF 00 00
0EBB LDX FE 00 02
0EBE INX 08 03
0EC0 STX FF 00 02
0EC3 LDX FE 00 06
0EC6 INX 08 03
0EC8 STX FF 00 06
0ECB LDX FE 00 08
0ECE INX 08 03
0ED0 STX FF 00 08
0ED3 DEX 09
0ED4 CPX BC 00 04 Check for end of data.
0ED7 NOP 01
0ED8 BEO 27 05
0EDA NOP 01 01
0EDD BRA 20 A9
0EDF LDX CE 07 20 Reset data positions.
0EE2 STX FF 00 02
0EE5 LDX CE 07 21
0EE8 STX FF 00 06
0EEB LDX FE 00 06 Crunch data into minimum
0EEE LDA A6 00 storage.
0EF0 LDX FE 00 02

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Reset temporary memory positions of start and end data.

Load memory position of beginning of data. Convert data to positive numbers.
0F5F   BRA   20 EC
0F61   LDX   FE 00 04  Decrement end of data memory
0F64   DEX   09  position by one.
0F65   STX   FF 00 04
0F68   RTS   39  Return from subroutine to
          Tiny Basic program Main
          Output.
"Multiderivative" (Assembly)

0E30 LDX CE 07 21 Initialize temporary memory
0E33 STX FF 00 02 positions for beginning of
data.
0E36 LDX CE 07 20
0E39 STX FF 00 06
0E3C LDX FE 00 02 Load Nth. data point.
0E3F LDAB E6 00
0E41 LDX FE 00 06 Load Nth.+1 data point.
0E44 LDAA A6 00
0E46 SBA 10 Subtract data points.
0E47 LDAB CE 80 Convert difference to
0E49 ABA 1B positive number.
0E4A LDAA A7 00
0E4C INX 08
0E4D STX FF 00 05 Store derivative data point
0E50 LDX FE 00 02 in current memory position.
0E53 INX 08
0E54 STX FF 00 02
0E57 CPX BC 00 04 Check for end of data.
0E59 BEQ 27 02
0E5C BRA 20 DE
0E5E CLC 0C
0E5F LDX FE 00 04 Decrement end of data memory
0E62 DEX 09 position by one.
0E63 STX FF 00 04
0E66 RTS 39 Return from subroutine to
Tiny Basic program Main
Output.

Initialise temporary memory positions for beginning of data.
Load Nth. data point.
Load Nth.+1 data point.
Subtract data points.
Convert difference to positive number.
Store derivative data point in current memory position.
Check for end of data.
Decrement end of data memory position by one.
Return from subroutine to Tiny Basic program Main Output.
Flowchart C-1. Apple/Isaac Input
2: Initialize Acquire

Input Data point → Convert %T to Abs. → Return to Apple Input

Test for end or range

YES
Average 10 data point over range → Initialize disk drive to Input

NO
Test for 10 date point

YES

NO

Stop

Flowchart C-1 (Cont)
"APPLE INPUT" (BASIC)

3 DIM B(20)
4 DIM A(2400)
5 M=1
6 Q=0
7 P=0
8 B(0)=0
10 PRINT "ENTER STARTING WAVE NUMBER POSITION OF INFRARED MONOCHROMATOR"
20 PRINT
30 PRINT "FOR THE ACCULAB 8 I.R. THIS WILL BE EITHER 4000 CM^-1 OR 2000 CM^-1"
40 PRINT
50 INPUT S
51 IF S=4000 THEN GOTO 70
52 IF S=2000 THEN GOTO 70
53 GOTO 30
60 PRINT
70 PRINT
80 PRINT "ENTER WAVE NUMBER RANGE TO BE STUDIED"
90 PRINT
100 PRINT "WAVE NUMBER MAXIMUM (CM^-1)"
110 PRINT
120 INPUT L
130 PRINT
140 PRINT "WAVE NUMBER MINIMUM (CM^-1)"
150 PRINT
160 INPUT D
163 PRINT
164 PRINT
165 IF L>D THEN GOTO 185
166 PRINT "RE-ENTER WAVE NUMBERS CORRECTLY"
167 PRINT
168 GOTO 80
180 PRINT
185 IF S>L GOTO 190
186 GOTO 166
190 PRINT "PRESS ONE OF THE SCAN SPEED BUTTONS ON THE ACCULAB 8"
200 PRINT
210 PRINT "ENTER THE SCAN SPEED"
215 PRINT "SLOW=1 ; MEDIUM=2 ; FAST=3"
220 PRINT
230 INPUT G
231 IF G=1 THEN C=700
233 IF G>3 GOTO 200
234 IF G=1 GOTO 200a
235 IF G=1 THEN C=700
237 & AOUT, (DV)=4095, (C#)=3
238 & AOUT, (DV)=0, (C#)=1
239 & AOUT, (DV)=0, (C#)=2

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240 PRINT
241 PRINT "ENTER SAMPLE NAME"
242 PRINT
243 INPUT N$
245 PRINT
250 & AOUT, (DV)=0, (C#)=1
260 & AOUT, (DV)=0, (C#)=2
261 PRINT
262 PRINT "PRESS THE SCAN BUTTON"
263 PRINT
264 PRINT "ARE YOU READY (Y OR N)"
265 INPUT E$
266 IF E$="Y" THEN GOTO 270
267 GOTO 261
270 F=S-L
275 Z=L-D
276 IF S=4000 THEN Z=Z/2
277 IF S=4000 THEN F=F/2
278 & AOUT, (DV)=4095, (C#)=1
279 & AOUT, (DV)=4095, (C#)=1
282 IF Z=1 THEN GOTO 270
284 PRINT "ARE YOU READY OR NIL"
285 INPUT E$
287 GOTO 281
288 IF E$="Y" THEN GOTO 270
270 F=S-L
275 Z=L-D
276 IF S=4000 THEN Z=Z/2
277 IF S=4000 THEN F=F/2
278 & AOUT, (DV)=4095, (C#)=1
279 & AOUT, (DV)=4095, (C#)=1
305 & CLRCOUNTER, (C#)=1
306 & COUNTERIN, (TV)=E
307 IF E=1 GOTO 305
309 & CLRCOUNTER, (C#)=1
310 & COUNTERIN, (TV)=W
312 IF W=0 THEN Q=0
315 IF W=0 GOTO 310
320 IF Q=1 GOTO 310
325 Q=Q+W
330 IF Q=F GOTO 350
335 Q=1
340 GOTO 310
350 GOSUB 2000
360 P=P+1
370 IF P=Z GOTO 1000
380 GOTO 310
1000 & AOUT, (DV)=0, (C#)=1
1010 PRINT
1011 PRINT "PLACE DATA DISK IN DRIVE #1"
1012 PRINT "ARE YOU READY"
1013 INPUT M$
1014 PRINT
1015 PRINT "DATA BEING STORED UNDER"
1020 PRINT "SAMPLE NAME ". N$
1025 LET D$=CHR$(4)
1030 PRINT D$:"OPEN":N$
1035 PRINT D$:"WRITE":N$
1040 FOR J=1 TO Z
1045 PRINT A(J)
1050 NEXT J
1055 PRINT D$:"CLOSE":N$
1060 END
"ACQUIRE" (BASIC)

2000 FOR I=1 TO 10
2020 & AIN, (TV)=X, (C#)=0
2030 B(I)=LOG(X)*-.434294483
2040 A(M)=A(M)+B(I)
2045 X=0
2050 NEXT I
2060 M=M+1
2065 O=1
2070 RETURN
Flowchart C-2: Data Analyzer
10  L=0
20  K=1750
30  P=0
500  DIM D(250), B(250), A(250)
505  INPUT N$
510  FOR  I=1  TO  10
520  PRINT  D(I)
530  NEXT  I
535  LET  D$=CHR$(4)
540  PRINT  D$;"OPEN:";N$
550  PRINT  D$;"READ:";N$
560  FOR  J=1  TO  200
570  INPUT  D(J)
580  NEXT  J
585  PRINT  D$;"CLOSE:";N$
585  FOR  I=1  TO  200
590  IF  L=ABS(D(I))  THEN  L=ABS(D(I))
595  NEXT  I
599  FOR  I=1  TO  200
600  B(I)=D(I)+L
605  NEXT  I
610  GOTO  620
610  PRH$
611  PRINT  "SMOOTHED DATA"
612  PRINT  N$
613  PRINT  "WAVENUMBER ABS."
614  FOR  I=60  TO  150
615  PRINT  K-I,B(I)
618  NEXT  I
619  PRH$
620  &  HIRES1
630  &  SCROLLSET
640  FOR  I=60  TO  190
645  FOR  J=1  TO  2
650  &  NXTPLT=B(I)*120
655  NEXT  J
660  NEXT  I
665  PRINT  "DATA SMOOTH AND PLOT?"
670  INPUT  M$
675  IF  M$="N"  GOTO  700
680  IF  M$="Y"  GOTO  1000
690  GOTO  665
700  PRINT  "DERIVATIVE ?"
710  INPUT  M$
720  IF  M$="Y"  GOTO  2000
730  IF  M$="N"  GOTO  6000
740  GOTO  700
1000  FOR  I=1  TO  197
1010  B(I)=B(I)+B(I+1)+B(I+2)
1020  B(I)=B(I)/3

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1030 NEXT I
1040 GOTO 610
2000 P=0
2005 INPUT Z
2006 TEXT
2010 PRINT "ENTER NUMBER OF DERIVATIVE"
2020 INPUT R
2022 FOR I=1 TO 200
2023 A(I)=B(I)
2024 NEXT I
2025 IF R=0 GOTO 6000
2030 FOR I=1 TO 10
2040 FOR J=1 TO 196
2050 A(J)=A(J+1)-A(J)
2060 NEXT J
2070 IF I=R GOTO 2082
2080 NEXT I
2082 PR#1
2084 PRINT N$,"DERIVATIVE =",R
2086 PRINT "WAVENUMBER DER. VALUE"
2088 FOR I=60 TO 150
2090 PRINT K-I,A(I)
2092 NEXT I
2094 PR#0
3000 FOR I=1 TO 190
3006 E=P
3010 IF P(ABS(A(I))) THEN P=ABS(A(I))
3060 NEXT I
3070 & HIRES1
3080 & SCROLLSET
3090 FOR I=70 TO 190
4000 FOR I=1 TO 2
4010 & NXTPLT=(A(I)+P)*(127/P)*.5
4020 NEXT J
4030 NEXT I
4035 & RETRACE
4040 'PRINT
4050 GOTO 2000
6000 END
REFERENCES


27. Heath Co. 10 bit D/A converter model EC-800-GC manual. #595-1371.


